

IN THE CLAIMS

- 1 1. (currently amended) A method of determining diffusion and relaxation
2 characteristics about a fluid in an earth formation using nuclear magnetic
3 resonance (NMR) comprising:
4 (a) applying a static magnetic field to the earth formation, said applied
5 static magnetic field producing an internal field gradient;
6 (b) applying a sequence of radio frequency (RF) pulses to said earth
7 formation;
8 (c) detecting magnetic resonance signals resulting from said first sequence,
9 substantially all of said magnetic resonance signals being affected by the
10 internal field gradient; and
11 (d) processing said detected signals for determining said diffusion and
12 relaxation characteristics, said determination taking into
13 account said internal field gradient.
14
- 1 2. (currently amended) The method of claim 1 wherein said sequence of RF pulses
2 further comprises:
3 (A) a first sequence of RF pulses associated with a first signal at a first field
4 gradient, and
5 (B) a second sequence of RF pulses associated with a second signal at a
6 second field gradient different from said first field gradient;
7 wherein said detected signals comprise said first signal and said second signal..

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1 3. (original) The method of claim 2 wherein said first and second field gradients
2 correspond to different regions of examination in said earth formation.

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1 4. (original) The method of claim 2 wherein said first and second pulse sequences
2 each comprise at least one initial pulse, a first portion that follows the at least one
3 initial magnetic field pulse, and a second portion that follows the first portion
4 such that the second portion refocuses a last echo of the first portion.

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1 5. (original) The method of claim 2 wherein

2 (i) said first portion comprises a modified CPMG sequence including a
3 plurality of refocusing pulses with a tipping angle less than 180° and
4 having a first time interval between adjacent refocusing pulses of said
5 first portion, and

6 (ii) said second portion comprises a plurality of refocusing pulses having a
7 second time interval between adjacent refocusing pulses.

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1 6. (original) The method of claim 2 wherein said first portion comprises one of (i) an
2 inversion recovery sequence, (ii) a driven equilibrium sequence, and, (iii) a
3 CPMG sequence.

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1 7. (original) The method of claim 5 further comprising applying an echo train

2 correction to said first and second signal.

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1 8. (original) The method of claim 5 further comprising at least one additional
2 repetition of (A) and (B) for a different value of said first time interval.

3

1 9. (original) The method of claim 5 further comprising repeating (i) for at least one
2 additional value of a time interval between refocusing pulses of said CPMG
3 sequence, said additional value being substantially equal to said second time
4 interval.

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1 10. (original) The method of claim 1 further determining at least one of (i) a total
2 porosity, (ii) clay bound water, (iii) bound volume irreducible, (iv) gas saturation,
3 and (v) oil saturation.

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1 11. (original) The method of claim 2 wherein said first sequence is of a form:

$$2 \quad W - 90_{\pm x} - TE_{long}/2 - \beta_{Y1} - TE_{long}/2 - echo_1 - TE_{long}/2 - \beta_{Y1} \\ - TE_{long}/2 - echo_2 - (TE/2 - \beta_{Y2} - TE/2 - echo)_j$$

3 where j is an echo number in a train, W is a wait time, TE_{long} is a diffusion editing
4 spacing, TE is the Carr-Purcell spacing, $90_{\pm x}$ and β_{Y1} (or β_{Y2}) are RF pulses
5 providing rotation angles of 90° and the β_{Y1} (or β_{Y2}) degrees of a magnetization
6 vector.

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1 12. (currently amended) The method of ~~claim 1~~ claim 2 wherein processing said first
2 ~~and said second signal~~ detected signals further comprises, for said first field
3 gradient and said second gradient, inverting said first and said second signals, to
4 obtain an equivalent amplitude spectrum of a T_2 distribution.

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1 13. (currently amended) The method of claim 12 wherein said processing said first
2 ~~and said second signal~~ detected signals further comprises inverting a T_2
3 distribution to obtain a generalized parameter.

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1 14. (original) The method of claim 13 wherein said generalized parameter $Z_i^{(j)}$ has a
2 form:

3
4
$$Z_i^{(j)} = \frac{C}{\gamma^2 G_e^2 D_i^j}$$

5 where C is a constant, γ is a gyromagnetic ratio, G_e is the effective field
6 gradient, and D_i^j is a diffusion coefficient.

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1 15. (currently amended) The method of claim 13 wherein said processing said first
2 ~~and said at least one additional signal~~ detected signals further comprises inverting
3 a plurality of said generalized parameters.

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1 16. (original) The method of claim 12 wherein at least one component of said

2 equivalent amplitude spectrum further comprises a plurality of diffusion
3 components.

4
1 17. (original) The method of claim 11 further comprising at least one additional
2 repetition of (b) and (c) for a different value of TE_{long} .

3
1 18. (original) The method of claim 2 wherein said first pulse sequence is of a form:
2 $180 - \tau_1 - 90_{\pm x} - [TE/2 - \beta_y - TE/2 - echo]_j$
3 wherein 180 is a 180° tipping pulse, τ is a wait time, TE is the Carr-Purcell
4 spacing, $90_{\pm x}$ and β_y are RF pulses providing rotation angles of 90° and β of
5 a magnetization vector

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1 19. (original) The method of claim 18 further comprising at least one additional
2 repetition of (A) and (B) for a different value of τ .

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1 20. (currently amended) An apparatus for determining diffusion and relaxation
2 characteristics about a fluid in an earth formation comprising:
3 (a) a magnet on a nuclear magnetic resonance (NMR) sensor conveyed in a
4 borehole in said earth formation, said magnet producing a static magnetic
5 field to in the earth formation with an internal field gradient therein;
6 (b) a transmitter on said NMR sensor ~~for applying~~ which applies a sequence
7 of radio frequency (RF) pulses to said earth formation;

- 8 (c) a receiver on said NMR sensor ~~for detecting~~ which detects magnetic
9 resonance signals resulting from said first sequence, substantially all of the
10 magnetic resonance signals being affected by the internal field gradient;
11 and
12 (d) a processor ~~for determining~~ which determines from said detected signals
13 said diffusion and relaxation characteristics, said determination taking into
14 account said internal field gradient.

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1 21. (currently amended) The apparatus of claim 20 wherein said transmitter applies:

2 (A) a first sequence of RF pulses associated with a first signal at a first field
3 gradient, and

4 (B) a second sequence of RF pulses associated with a second signal at a
5 second field gradient different from said first field gradient;

6 wherein said magnetic resonance signals comprise said first signal and said
7 second signal.

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1 22. (original) The apparatus of claim 21 wherein said first and second field gradients
2 correspond to different regions of examination in said earth formation.

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1 23. (currently amended) The apparatus of claim 21 wherein said first sequence of RF
2 pulses and the second sequence of RF pulses ~~pulse-sequences~~ each comprise at
3 least one initial pulse, a first portion that follows the at least one initial magnetic

4 field pulse, and a second portion that follows the first portion such that the second
5 portion refocuses a last echo of the first portion.

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1 24. (currently amended) The apparatus of ~~claim 21~~ claim 23 wherein

2 (i) said first portion comprises a modified CPMG sequence including a
3 plurality of refocusing pulses with a tipping angle less than 180° and
4 having a first time interval between adjacent refocusing pulses of said
5 first portion, and

6 (ii) said second portion comprises a plurality of refocusing pulses having a
7 second time interval between adjacent refocusing pulses.

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1 25. (currently amended) The apparatus of ~~claim 21~~ claim 23 wherein said first portion
2 comprises one of (i) an inversion recovery sequence, (ii) a driven equilibrium
3 sequence, and (iii) a CPMG sequence.

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1 26. (original) The apparatus of claim 24 wherein said processor further applies further
2 an echo train correction to said first and second signal.

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1 27. (original) The apparatus of claim 24 wherein said transmitter further performs at
2 least one additional repetition of (A) and (B) for a different value of said first time
3 interval.

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1 28. (original) The apparatus of claim 24 wherein said processor further repeats (i) for
 2 at least one additional value of a time interval between refocusing pulses of said
 3 CPMG sequence, said additional value being substantially equal to said second
 4 time interval.

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1 29 (original) The apparatus of claim 20 wherein said processor further determines at
 2 least one of (i) a total porosity, (ii) clay bound water, (iii) bound volume
 3 irreducible, (iv) gas saturation, and, (v) oil saturation.

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1 30. (original) The apparatus of claim 21 wherein said first sequence is of a form:

$$\begin{aligned}
 &W - 90_{\pm x} - TE_{long} / 2 - \beta_Y - TE_{long} / 2 - echo_1 - TE_{long} / 2 - \beta_Y \\
 &- TE_{long} / 2 - echo_2 - (TE / 2 - \beta_Y - TE / 2 - echo)_j
 \end{aligned}$$

3 where j is an echo number in a train, W is a wait time, TE_{long} is a diffusion editing
 4 spacing, TE is the Carr-Purcell spacing, $90_{\pm x}$ and β_Y are RF pulses providing
 5 rotation angles of 90^0 and the β of a magnetization vector.

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1 31 (original) The apparatus of claim 20 wherein said processor further obtains an
 2 equivalent amplitude spectrum of a T_2 distribution.

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1 32. (currently amended) A system for use in a borehole in an earth formation
 2 comprising:

- 3 (a) a conveyance device ~~for conveying~~ which conveys a nuclear magnetic
4 resonance (NMR) sensor into said borehole;
- 5 (b) a magnet on said ~~NMR~~ NMR sensor, said magnet applying a static
6 magnetic field in said earth, said static magnetic field having an internal
7 gradient;
- 8 (b) a transmitter on said NMR sensor ~~for applying~~ which applies
9 radio-frequency (RF) magnetic field pulses to said formation and
10 ~~producing~~ produces signals resulting from a T_2 distribution spectrum of
11 said earth formation, at least one component of said T_2 spectrum further
12 comprising a plurality of diffusion coefficients, said signals being
13 substantially affected by the internal field gradient;
- 14 (c) a receiver on said NMR sensor ~~for receiving~~ which receives said produced
15 signals;
- 16 (d) a processor ~~for processing~~ which processes said received signals and
17 ~~determining~~ determines therefrom said T_2 distribution and said plurality of
18 diffusion coefficients, said determination accounting for said internal
19 gradient.

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1 33. (original) The system of claim 32 wherein said conveyance device is one of (i) a
2 wireline, (ii) a drillstring, and, (iii) coiled tubing..

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1 34. (currently amended) A method of analyzing an earth formation comprising:

- 2 (a) applying a static magnetic field to the earth formation, said applied
3 static magnetic field producing an internal field gradient in said earth
4 formation;
5 (b) applying a first sequence of radio frequency (RF) pulses to said earth
6 formation and obtaining a first signal associated with a first value of a
7 field gradient;
8 (c) applying a second sequence of radio frequency (RF) pulses to said earth
9 formation and obtaining a second signal associated with a second value of
10 a field gradient; and
11 (d) processing said first and second signals for determining at least one of (A)
12 a diffusion characteristic of said earth formation, and, (ii) a relaxation
13 characteristic of said earth formation, said determination taking into
14 account said internal field gradient;
15 wherein said first and second signals being substantially affected by the internal
16 field gradient..

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1 35. (original) The method of claim 34 wherein said first and second field gradients
2 correspond to different regions of examination in said earth formation.
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1 36. (original) The method of claim 34 said first and second pulse sequences each
2 comprise at least one initial pulse, a first portion that follows the at least one

3 initial magnetic field pulse, and a second portion that follows the first portion
4 such that the second portion refocuses a last echo of the first portion.
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1 37. (currently amended) An apparatus for use in a borehole in an earth formation
2 comprising:

- 3 (a) a magnet ~~for applying~~ which applies a static magnetic field to the earth
4 formation, said applied static magnetic field producing an internal field
5 gradient in said earth formation;
- 6 (b) a transmitter ~~for applying~~ which applies a first pulse sequence and a
7 second sequence of radio frequency (RF) pulses to said earth formation;
- 8 (c) a receiver ~~for obtaining~~ which obtains a first signal and a second signal
9 resulting from said first and second sequence of RF pulses, said first and
10 second signals associated with a first and second value of a field gradient
11 in said earth formation and affected by the internal field gradient; and
- 12 (d) a processor for determining from said first and second signal at least one
13 of (A) a diffusion characteristic of said earth formation, and, (ii) a
14 relaxation characteristic of said earth formation, said determination taking
15 into account said internal field gradient.

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1 38. (original) The apparatus of claim 37 wherein said first and second field gradients
2 correspond to different regions of examination in said earth formation.
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1 39. (original) The apparatus of claim 37 said first and second pulse sequences each
2 comprise at least one initial pulse, a first portion that follows the at least one
3 initial magnetic field pulse, and a second portion that follows the first portion
4 such that the second portion refocuses a last echo of the first portion.

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1 40. (original) The apparatus of claim 37 further comprising a conveyance device
2 selected from (i) a wireline, (ii) a drilling tubular, and, (iii) coiled tubing.

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1 41. (original) The method of claim 39 wherein said first portion comprises one of (i)
2 an inversion recovery sequence, (ii) a driven equilibrium sequence, (iii) a CPMG
3 sequence, and, (iv) a modified CPMG sequence having a refocusing pulse with a
4 tipping angle less than 180° .

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